

Negentropic Planar Symmetry Detector Supplementary Material

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1 Details of a Loy and Eklundh's Method Assessment

In this section we present the details of Loy and Eklundh's method [1] assessment. The pseudocode is given in Algorithm 1. The input parameters are an image I and a scaling factor $sf \in (0, 1]$. In our experiments we have set $dist_max$ as $1/64$ of the original image resolution, this parameter is used to determine the most centred rotation in an image.

[2] utilizes the right-handed coordinate system, while in our method we use the left-handed one. Therefore in line 6 of the algorithm we transform the results to the left-handed system and take modulo 180 to keep angles between 0° and 180° .

2 Details of a Shen-Ip Symmetry Detector Assessment

Shen-Ip Symmetry Detector [3] is based on generalized complex (GC) moments given by

$$GC_{p,q} = \frac{1}{2\pi} \int_0^{2\pi} \int_0^\infty I(r, \theta) (r^{p+1} \exp(iq\theta)) dr d\theta.$$

In our implementation of Shen-Ip method we map an image I onto a unit disc so that $r \in [0, 1]$ and $\theta \in [0, 2\pi]$ and utilize a discrete estimator of a GC moment,

$$\widehat{GC}_{p,q} = \frac{1}{2\pi} \sum_0^{2\pi} \sum_0^1 I(r, \theta) r^{p+1} \exp(iq\theta).$$

We have found, however, a certain problem with using GC moments. Moments with repetition q equal to a multiple of 4 reach significantly higher values than other moments. We have run our experiments including and excluding these moments, and the latter yielded higher detection rates.

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Algorithm 1 Execution of Loy and Eklundh's Algorithm

```
1: procedure LOYEKLUNDH( $I, sf$ )
2:    $loy\_refl \leftarrow [1]$  call for mirror symmetry detection in  $I$  scaled by  $sf$ 
3:    $loy\_rot \leftarrow [1]$  call for rotational symmetry detection in  $I$  scaled by  $sf$ 
4:   if NBOFROWS( $loy\_refl$ ) > 0 then
5:      $angle \leftarrow loy\_refl[1][2]$  ▷ the angle of a dominant symmetry
6:      $tilt\_angle \leftarrow (angle + 90) \bmod 180$ 
7:      $order\_refl \leftarrow$  NBOFROWS( $loy\_refl$ )
8:   else
9:      $tilt\_angle \leftarrow -1$ 
10:     $order\_refl \leftarrow 0$ 
11:   end if
12:    $rot\_idx \leftarrow$  an index of a row in  $loy\_rot$  that contains rotational symmetry whose centre is
    the closest to the centre of an image and no further away than a predefined threshold  $dist\_max$ .
    If no such symmetry was found then 0.
13:   if  $rot\_idx > 0$  then
14:      $order\_rot \leftarrow loy\_rot[rot\_idx][3]$ 
15:   else
16:      $order\_rot \leftarrow 1$ 
17:   end if
18:   return  $order\_refl, angle, order\_rot$ 
19: end procedure
```

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References

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- [3] D. Shen, H. H. Ip, K. K. Cheung, E. K. Teoh, Symmetry detection by generalized complex (gc) moments: a close-form solution, IEEE Trans Pattern Anal Mach Intell 21 (5) (1999) 466–476.